

**Amendments to the Claims:**

This listing of claims will replace all prior versions, and listings, of claims in the application:

**Listing of Claims:**

Claim 1 (Previously Presented) A car navigation system comprising:

- a position detector for detecting a position of a vehicle;
- an input unit for receiving a facilities request from a user;
- a land mark search unit for searching for land mark facilities to satisfy the facilities request in a land mark database;
- a map summarizing unit for generating a summary road map by applying a summarizing operation over a main road including a running route and by applying an icon representing any found land mark facilities satisfying the facilities request; and
- a display unit for displaying the summary road map together with a mark indicative of the vehicle position.

Claim 2 (Previously Presented) The car navigation system according to claim 1, wherein the display unit displays an attribute information about a land mark facility specified by the input unit.

Claim 3 (Previously Presented) A car navigation system comprising:

- a position detector for detecting a position of a vehicle;

a search unit for searching for a route between the detected vehicle position and a specified target position or a specified departure position and the specified target position under set conditions;

a map summarizing unit for generating a summary road map by simplifying the route between the detected vehicle position and the specified target position or the specified departure position and the specified target position with broken lines; and

a display unit for displaying the summary road map of the simplified route.

Claim 4 (Previously Presented) The car navigation system according to claim 3, wherein the searching unit also searches for another route between said the detected vehicle position and the specified target position or the specified departure position and said the specified target position under conditions other than the set conditions, and the display unit displays the summary road map of all the other routes between the detected vehicle position and the specified target position or the specified departure position and the specified target position searched by the search unit by simplified broken lines.

Claim 5 (Previously Presented) The car navigation system according to claim 3, further comprising a communication unit for receiving traffic information, and wherein the display unit displays the traffic information received by the communication unit on the summary road map with respect to the corresponding route displayed thereon.

Claim 6 (Previously Presented) The car navigation system according to claim 5, wherein the display unit displays a detour responsive to the traffic information indicating a blockage of passage of the vehicle on the summary road map.

Claim 7 (Cancelled)

Claim 8 (Previously Presented) The car navigation system according to claim 6, wherein the display unit displays two windows of the summary road map and of the road map when traffic information which blocks the passage of the vehicle is received by the communication unit.

Claim 9 (Previously Presented) A car navigation system comprising:  
a position detector for detecting a current position of a vehicle;  
an input unit for inputting a target position;  
a search unit for searching for a running route on the basis of the detected current position and the inputted target position;  
a map summarizing unit for generating a summary road map from the current vehicle position to a next turning corner on the searched running route; and  
a display unit for displaying the summary road map,  
wherein, when the current vehicle position arrives at a position within a predetermined range from the next turning corner, the display unit displays the summary road map from the current vehicle position to the next turning corner with a mark of the current vehicle position.

Claim 10 (Previously Presented) The car navigation system according to claim 9, wherein the predetermined range is broader than a display range of a magnified road map displayed for the next turning corner.

Claim 11 (Previously Presented) The car navigation system according to claim 3, wherein the vehicle position is displayed by a mark in the summary road map.

Claim 12 (Previously Presented) The car navigation system according to claim 3, wherein roads displayed in the summary road map are displayed as made linear and roads which meet at an intersection are displayed as made orthogonal to each other.

Claim 13 (Previously Presented) The car navigation system according to claim 3, wherein the display unit displays the simplified route without a map.

Claim 14 (Previously Presented) The car navigation system according to claim 8, wherein the display unit switches to a road map display when the vehicle position shifts to the detour.

Claim 15 (Previously Presented) The car navigation system according to claim 3, wherein the display unit displays a road map, and the road map is a two-dimensional road map or a bird's eye view road map or a three-dimensional road map.

Claim 16 (Previously Presented) The car navigation system according to claim 9, wherein the display unit displays a window of the summary road map with a window of a road map including the searched running route.

Claim 17 (Previously Presented) The car navigation system according to claim 9, wherein the display unit displays a road map, and the road map is a two-dimensional road map or a bird's eye view road map or three-dimensional road map.